

# Chapter 10

## Lecture 10

### 10.1 Connections on manifolds - 2 -

#### 10.1.1 Characterization of symmetric connections

**Proposition 10.1 (Characterization of symmetric connections)**

Let  $D(-, -)$  be a connection on a manifold  $\mathcal{M}, \mathcal{F}$  and  $(U, \phi) \in \mathcal{F}$  a chart of  $\mathcal{M}$  with coordinate functions  $(x^1, \dots, x^m)$ . The following conditions are equivalent:

1.  $D(-, -)$  is symmetric;
2.  $D\left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}\right) = D\left(\frac{\partial}{\partial x^j}, \frac{\partial}{\partial x^i}\right)$ ;
3.  $\Gamma_{ij}^k = \Gamma_{ji}^k$ .

**Proof:**

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1  $\Rightarrow$  2 Let us consider a symmetric connection. In a coordinate basis of  $\mathcal{M}_m$ , as is the one induced by the given chart, the Lie Brackets of two arbitrary basis vectors vanish, i.e.

$$\left[ \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right] = 0.$$

Thus

$$D\left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}\right) - D\left(\frac{\partial}{\partial x^j}, \frac{\partial}{\partial x^i}\right) = 0$$

or

$$D\left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}\right) = D\left(\frac{\partial}{\partial x^j}, \frac{\partial}{\partial x^i}\right).$$

□

2  $\Rightarrow$  3 If we express

$$D\left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}\right) = D\left(\frac{\partial}{\partial x^j}, \frac{\partial}{\partial x^i}\right)$$

in terms of the connection symbols, the above equality becomes

$$\sum_k^{1,m} \left( \Gamma_{ij}^k - \Gamma_{ji}^k \right) \frac{\partial}{\partial x^k} = 0.$$

But, since  $\{\partial/\partial x^k\}_{k=1,\dots,m}$  is a basis of  $\mathcal{M}_{\mathbf{m}}$  at each point  $\mathbf{m} \in U \subset \mathcal{M}$ , the  $\partial/\partial x^k$  are linearly independent, i.e.

$$\Gamma_{ij}^k - \Gamma_{ji}^k = 0 \quad \Rightarrow \quad \Gamma_{ij}^k = \Gamma_{ji}^k.$$

□

3  $\Rightarrow$  1 We consider to arbitrary vector fields  $\mathbf{V}$  and  $\mathbf{W}$  and write them in a coordinate basis associated to a given chart  $(U, \phi)$  with coordinate functions  $(x_1, \dots, x_m)$ :

$$\begin{aligned} \mathbf{V} &= \sum_i^{1,m} v_i \frac{\partial}{\partial x_i} \\ \mathbf{W} &= \sum_j^{1,m} w_j \frac{\partial}{\partial x_j} \end{aligned} \quad (10.1)$$

We first compute

$$\begin{aligned} D(\mathbf{V}, \mathbf{W}) &= D\left(\sum_i^{1,m} v_i \frac{\partial}{\partial x_i}, \sum_j^{1,m} w_j \frac{\partial}{\partial x_j}\right) \\ &= \sum_{i,j}^{1,m} D\left(v_i \frac{\partial}{\partial x_i}, w_j \frac{\partial}{\partial x_j}\right) \\ &= \sum_{i,j}^{1,m} v_i D\left(\frac{\partial}{\partial x_i}, w_j \frac{\partial}{\partial x_j}\right) \\ &= \sum_{i,j}^{1,m} \left[ v_i \frac{\partial w_j}{\partial x_i} \frac{\partial}{\partial x_j} + v_i w_j D\left(\frac{\partial}{\partial x_i}, \frac{\partial}{\partial x_j}\right) \right] \\ &= \sum_{i,j}^{1,m} v_i \frac{\partial w_j}{\partial x_i} \frac{\partial}{\partial x_j} + \sum_{i,j,k}^{1,m} \Gamma_{ij}^k v_i w_j \frac{\partial}{\partial x^k}. \end{aligned}$$

Then, by exchanging  $\mathbf{V}$  and  $\mathbf{W}$  we also obtain

$$D(\mathbf{W}, \mathbf{V}) = \sum_{i,j}^{1,m} w_j \frac{\partial v_i}{\partial x_j} \frac{\partial}{\partial x^i} + \sum_{i,j,k}^{1,m} \Gamma_{ji}^k v^i w^j \frac{\partial}{\partial x^k},$$

so that

$$\begin{aligned} D(\mathbf{V}, \mathbf{W}) - D(\mathbf{W}, \mathbf{V}) &= \\ &= \sum_{i,j}^{1,m} \left[ v_i \frac{\partial w_j}{\partial x_i} \frac{\partial}{\partial x^j} - w_j \frac{\partial v_i}{\partial x_j} \frac{\partial}{\partial x^i} \right] + \\ &\quad + \sum_{i,j,k}^{1,m} \left( \Gamma_{ji}^k - \Gamma_{ij}^k \right) v^i w^j \frac{\partial}{\partial x^k} \\ &= \sum_{i,j}^{1,m} \left[ v_i \frac{\partial w_j}{\partial x_i} \frac{\partial}{\partial x^j} - w_j \frac{\partial v_i}{\partial x_j} \frac{\partial}{\partial x^i} \right] \quad (10.2) \end{aligned}$$

since by the assumptions,  $\Gamma_{ij}^k = \Gamma_{ji}^k$ . We now compute the commutator, remembering in the first step result 1. of proposition 8.4:

$$\begin{aligned}
 [\mathbf{V}, \mathbf{W}] &= \left[ \sum_i^{1,m} v^i \frac{\partial}{\partial x^i}, \sum_j^{1,m} w^j \frac{\partial}{\partial x^j} \right] \\
 &= \sum_{i,j}^{1,m} v^i w^j \left[ \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right] + \\
 &\quad + \sum_{i,j}^{1,m} v^i \frac{\partial w^j}{\partial x^i} \frac{\partial}{\partial x^j} - \sum_{i,j}^{1,m} w^j \frac{\partial v^i}{\partial x^j} \frac{\partial}{\partial x^i} \\
 &= \sum_{i,j}^{1,m} \left[ v^i \frac{\partial w^j}{\partial x^i} \frac{\partial}{\partial x^j} - w^j \frac{\partial v^i}{\partial x^j} \frac{\partial}{\partial x^i} \right] \quad (10.3)
 \end{aligned}$$

The first term in the equation before the last vanishes since we are in a coordinate basis and we thus see from (10.2) and (10.3) that

$$D(\mathbf{V}, \mathbf{W}) - D(\mathbf{W}, \mathbf{V}) = [\mathbf{V}, \mathbf{W}],$$

i.e. the connection is symmetric.

This completes the proof. □

## 10.1.2 Smooth curves and covariant derivative along a curve

### Definition 10.1 (Smooth curve on a manifold)

Let us consider a manifold  $(\mathcal{M}, \mathcal{F})$ . A smooth curve on  $\mathcal{M}$  is a differentiable map

$$\sigma : [a, b] \longrightarrow \mathcal{M}$$

such that  $\sigma(t) \in \mathcal{M}$ . The tangent vector to the curve is denoted by  $\dot{\sigma}(t)$ , which is defined as

$$\dot{\sigma}(t) = d\sigma \rfloor_t \left( \frac{d}{dr} \Big|_t \right).$$

Remember that the differential of  $\sigma(t)$  is a map

$$d\sigma \rfloor_t : \mathbb{R}_t \cong \mathbb{R} \longrightarrow \mathcal{M}_{\sigma(t)},$$

which maps tangent vectors in  $\mathbb{R}_t$  into tangent vectors of  $\mathcal{M}_{\sigma(t)}$ . This helps us in giving a precise characterization of the tangent vector  $\dot{\sigma}(t)$ . Indeed let us consider a coordinate neighborhood  $(U, \phi)$  on  $\mathcal{M}$ , where  $\phi$  is associated to the coordinates  $(x^1, \dots, x^m)$ . We fix as usual the coordinate basis on the tangent spaces of points in  $U$ . The components of the vector  $\dot{\sigma}(t)$  (which is a map from  $C^\infty(\mathcal{M})$  into  $\mathbb{R}$ ) are

$$(\dot{\sigma}(t))(x^i) = \left( d\sigma \rfloor_t \left( \frac{d}{dr} \Big|_t \right) \right) (x^i) = \frac{d}{dr} \Big|_t (x^i \circ \sigma) = \frac{d\sigma^i}{dr} \Big|_t \stackrel{\circ}{=} \frac{d\sigma^i(t)}{dt} \quad ,$$

where  $\sigma^i = x^i \circ \sigma$  is the  $i$ -th coordinate component of the map  $\sigma$  defining the curve. We can thus write

$$\dot{\sigma}(t) = \sum_i^{1,m} \left. \frac{d\sigma^i}{dr} \right|_t \left. \frac{\partial}{\partial x^i} \right|_{\sigma(t)} \stackrel{\circ}{=} \sum_i^{1,m} \frac{d\sigma^i(t)}{dt} \left. \frac{\partial}{\partial x^i} \right|_{\sigma(t)}.$$

In what follows we are also going to use the notation  $x^i(t)$  in place of  $\sigma^i(t)$  for the components of the curve.

**Proposition 10.2 (Covariant derivative along a curve)**

Let  $\sigma(t) : [a, b] \rightarrow \mathcal{M}$  be a differentiable curve on a manifold  $(\mathcal{M}, \mathcal{F})$  with connection  $D(-, -)$ . Let  $\mathbf{V}(t)$  be a differentiable vector field along  $\sigma$ . There exists one and only one map which associates to a vector field  $\mathbf{V}$  along  $\sigma$  another vector field  $D\mathbf{V}/dt$  along  $\sigma$ , the covariant derivative of  $\mathbf{V}$  along  $\sigma$ , such that:

1.  $\frac{D(\mathbf{V} + \mathbf{W})}{dt} = \frac{D\mathbf{V}}{dt} + \frac{D\mathbf{W}}{dt}$ ;
2.  $\forall f : [a, b] \rightarrow \mathbb{R}$  we have  $\frac{D(f\mathbf{V})}{dt} = \frac{df}{dt}\mathbf{V} + f\frac{D\mathbf{V}}{dt}$ ;
3. if  $\mathbf{Y} \in \mathcal{V}(\mathcal{M})$  is a vector field on  $\mathcal{M}$  such that  $\mathbf{V}(t) = Y(\sigma(t))$  then

$$\frac{D\mathbf{V}}{dt} = D(\dot{\sigma}(t), \mathbf{Y})_{\sigma(t)}. \quad (10.4)$$

**Proof:**

Let us choose a chart  $(U, \phi) \in \mathcal{F}$  on the manifold  $(\mathcal{M}, \mathcal{F})$  with coordinate functions  $(x^1, \dots, x^m)$ . and let us consider a curve  $\sigma(t) = (x^1(t), \dots, x^m(t))$ . We then have

$$\dot{\sigma}(t) = \sum_i^{1,m} \frac{dx^i(t)}{dt} \frac{\partial}{\partial x^i}.$$

To prove the existence we use property 3. as an ansatz, i.e. we define

$$\frac{D\mathbf{V}}{dt} \stackrel{\text{def.}}{=} D(\dot{\sigma}(t), \mathbf{V})_{\sigma(t)};$$

this is a good definition since the operation defined by the connection is local, i.e. it depends only on the values of the vector fields at a given point and thus it makes sense for each vector field which is defined at that point. Moreover we have:

$$\begin{aligned} \frac{D(\mathbf{V} + \mathbf{W})}{dt} &= D(\dot{\sigma}(t), \mathbf{V} + \mathbf{W})_{\sigma(t)} \\ &= D(\dot{\sigma}(t), \mathbf{V})_{\sigma(t)} + D(\dot{\sigma}(t), \mathbf{W})_{\sigma(t)} \\ &= \frac{D\mathbf{V}}{dt} + \frac{D\mathbf{W}}{dt}, \end{aligned}$$

so that 1. is satisfied. Then we have

$$\begin{aligned} \frac{D(f\mathbf{V})}{dt} &= D(\dot{\sigma}(t), f\mathbf{V})_{\sigma(t)} \\ &= (\dot{\sigma}(t))(f)\mathbf{V} + fD(\dot{\sigma}(t), \mathbf{V})_{\sigma(t)} \\ &= \sum_i^{1,m} \frac{dx^i(t)}{dt} \frac{\partial}{\partial x^i}(f) + fD(\dot{\sigma}(t), \mathbf{V})_{\sigma(t)} \\ &= \frac{df}{dt}\mathbf{V} + f\frac{D\mathbf{V}}{dt} \end{aligned}$$

and 2. is also satisfied. 3., of course, holds by definition, so the only property we still have to prove is uniqueness. To establish it we rewrite  $D\mathbf{V}/dt$  using the local expression above for  $\dot{\sigma}(t)$  and also writing locally the vector field along  $\sigma(t)$  as

$$\mathbf{V}(t) = \sum_j^{1,m} v^j(t) \frac{\partial}{\partial x^j}.$$

Then from equation (10.4) we can obtain the following chain of equalities:

$$\begin{aligned} \frac{D\mathbf{V}}{dt} &= \frac{D\left(\sum_j^{1,m} v^j(t) \frac{\partial}{\partial x^j}\right)}{dt} \\ &= \sum_j^{1,m} \left( \frac{dv^j(t)}{dt} \frac{\partial}{\partial x^j} + v^j(t) \frac{D(\partial/\partial x^j)}{dt} \right) \\ &= \sum_j^{1,m} \left[ \frac{dv^j(t)}{dt} \frac{\partial}{\partial x^j} + v^j(t) D\left(\dot{\sigma}(t), \frac{\partial}{\partial x^j}\right) \right] \\ &= \sum_j^{1,m} \left[ \frac{dv^j(t)}{dt} \frac{\partial}{\partial x^j} + v^j(t) D\left(\sum_i^{1,m} \frac{dx^i(t)}{dt} \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}\right) \right] \\ &= \sum_k^{1,m} \frac{dv^k(t)}{dt} \frac{\partial}{\partial x^k} + \sum_{i,j}^{1,m} v^j(t) \frac{dx^i(t)}{dt} D\left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}\right) \\ &= \sum_k^{1,m} \frac{dv^k(t)}{dt} \frac{\partial}{\partial x^k} + \sum_{i,j}^{1,m} v^j(t) \frac{dx^i(t)}{dt} \Gamma_{ij}^k \frac{\partial}{\partial x^k} \\ &= \sum_k^{1,m} \left( \frac{dv^k(t)}{dt} + \sum_{i,j}^{1,m} \Gamma_{ij}^k \frac{dx^i(t)}{dt} v^j(t) \right) \frac{\partial}{\partial x^k}. \end{aligned} \quad (10.5)$$

We thus see that the covariant derivative along  $\sigma(t)$  is completely determined by the connection coefficients in a unique way, i.e., given the connection, it is unique. This completes the proof.

□

